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1.0 PROTOCOL APPROVAL:

Signing of this approval page of Protocol indicates agreement with the qualification approach described in this document. If modification to the qualification approach becomes necessary, an addendum shall be prepared and approved. The protocol cannot be used for execution unless approved by the following signatories.

This Installation Qualification protocol of Carton Packing machine has been reviewed and approved by the following signatories:

FUNCTION	NAME	DESIGNATION	DEPARTMENT	SIGNATURE	DATE
PREPARED BY			QUALITY ASSURANCE		
			QUALITY ASSURANCE		
REVIEWED BY			ENGINEERING		
			PRODUCTION		
APPROVED			HEAD OPERATION		
BY			QUALITY ASSURANCE		



2.0 **OVERVIEW:**

2.1 OBJECTIVE:

The objective of developing and executing this protocol is to collect sufficient data pertaining to the Carton Packing machine and define the qualification requirements and acceptance criteria for the unit. Successful completion of these qualification requirements will provide assurance that the Carton Packing machine was installed as required in packing line.

The Qualification of Carton Packing machine performed in view of line II of Soft gel packing hall of manufacturing facility.

2.2 PURPOSE:

The purpose of this protocol is to establish documentary evidence to ensure that the Carton Packing machine received matches the Design specification and also to ensure that it is properly and safely installed.

2.3 SCOPE:

The installation qualification protocol shall be followed for installation qualification of Carton Packing machine. This protocol defines the methods and documentation that shall be used to evaluate the system installation in accordance with the specifications and intended use. Successful implementation of this protocol shall verify that the systems installed meet the requirements specified.

2.4 **RESPONSIBILITY:**

In accordance with protocol, following functions shall be responsible for the qualification of system.

Execution Team (Comprising members from Production, Engineering and Quality Assurance) and their responsibilities are following:

- Prepares the qualification protocol.
- Ensures that the protocol is in compliance with current policies and procedures on system Qualification.
- > Distributes the finalized protocol for review and approval signatures.



- Execution of Qualification protocol.
- > Review of protocol, the completed qualification data package, and the final report.
- The installation checks, calibration, SOP identification, identification features, identification of utility supply shall be carried out by engineering persons.
- The production operator / supervisor shall carry out the cleaning and operation of machine.

Head – Production/ Engineering:

- > Review of protocol, the completed qualification data package, and the final report.
- > Assist in the resolution of validation deficiencies.

Head – Operation and Quality Assurance:

Review and approval of protocol, the completed qualification data package, and the final report.



2.5 EXECUTION TEAM:

The satisfactory installation of the Carton Packing machine shall be verified by executing the qualification studies described in this protocol. The successfully executed protocol documents that the Carton Packing machine is installed satisfactorily.

Execution team is responsible for the execution of installation qualification of Carton Packing machine and Execution team comprises of:

NAME	DESIGNATION	DEPARTMENT	SIGNATURE	DATE

3.0 ACCEPTANCE CRITERIA:

- 3.1 The Carton Packing machine shall meet the system description given in design specification.
- 3.2 The Carton Packing machine shall meet with the acceptance criteria mentioned under the topic "Identification of major components".
- 3.3 Safety feature, Utility & calibration shall be identified.



4.0 **REVALIDATION CRITERIA:**

The machine has to be revalidated if

- There are any major changes, which affect the performance of the equipment.
- After major breakdown, maintenance is carried out.
- As per revalidation date and schedule.

5.0 INSTALLATION QUALIFICATION PROCEDURE

5.1 EQUIPMENT DESCRIPTION:

Equipment Name	:	Carton Packing machine					
Supplier / Manufacturer	:	ACG Pampac Machines Pvt. Ltd.					
Model	:	CP 150					
Machine No.	:						
Machine Type	:	Continuous motions automatic Cartoning machine.					
Carton size range that can be	:		Width	Height	Length		
handled		Minimum	20 mm	14 mm	65 mm		
		Maximum	100 mm	65 mm	180 mm		
Suitable working temperature range	:	18-30 ⁰ C					
Noise level	:	80 dB (Appro	x.)				
Suitable humidity range for the machine	:	45 to 90 % RH					
Output	:	Up to 150 cartons/ minute (Depending on product shape & size)					
Electrical supply	:	415 V (±10%), 50 Hz					
Compressed air (Dry)	:	6 bar max.					
Location	:	Line of Soft g	el Packing ha	11			



Main Functional Areas:

The main modules in the basic machine are as follows:

- Carton loading magazine
- Carton pick up
- Carton discharge
- Printing station
- Carton chain
- Product chain
- Empty carton rejection system
- Ink embossing station
- Blister transfer system
- Pre-folded Leaflet Transfer system

The cartoning machine model CP 150 is a continuous motion machine particularly suited for automatic cartoning of unit product like ampoules, bottles, tubes & blisters.

The machine meets the requirement of high volume production, giving an output of up to 150 cartons /minute depending upon application.

Various kinds of supplementary attachments like leaflet inserter, empty carton ejection, sensing device and make this machine as one that gives solution to many automation requirements.

The machine can be centrally adjusted to take care of various carton lengths. Also it can be easily adjusted for different widths and height of cartons.

Cartons loaded (manually) into the carton magazine are picked up by Oscillating pick up arms and are loaded into the carton chain. Carton moves along with the carton chain. During this process cartons are closed from rear and front flaps are open. Cartons are carried to product loading zone where product is loaded automatically. Cartons are closed from the front and are discharged through discharge belt.



5.2 INSTRUCTION FOR FILLING THE CHECKLIST

- 5.2.1 In case of identification of major component actual observation should be written in specified location.
- 5.2.2 In case of the compliance of the test actual observation should be written in specified location.
- 5.2.3 For identification of utilities actual observation should be written in specified location.
- 5.2.4 Give the detailed information in the summary and conclusion part of the installation Qualification report.
- 5.2.5 Actual observation of the component should be written in specified location.
- 5.2.6 Whichever column is blank or not used 'NA' shall be used.



5.3 INSTALLATION CHECKLIST:

Installation checklist is as follows:

S.No.	Statement	Method of Verification	Actual observation	Checked By Sign/Date
1.	Verify the purchase order copy and PO no. Shall be written in observation column	Physically		
2.	Verify that the "As Built" drawing is complete and represents the design concept.	Physically		
3.	Verify that major components are securely anchored and shock proof.	Physically		
4.	Verify that there is sufficient room provided for servicing.	Physically		
5.	Verify that all piping and electrical connections are done according to the drawings.	Physically		
6.	All access ports are examined and cleared of any debris.	Physically		
7.	Safe electrical connections.	Physically		
8.	Sufficient room provided for maintenance.	Physically		
9.	Equipment identification nameplate visible.	Physically		
10.	Units installed on foundation are secure in place as per manufacturer's recommendations.	Physically		
11.	Verify that there is no observable physical damage	Physically		

Remark: -----

Reviewed by (Sign/Date)



5.4 IDENTIFICATION OF MAJOR COMPONENTS:

Describe each critical component and check them and fill the inspection checklist.

System Components	Desi	gn Specification	Method of Verification	Actual Observation	Checked By Sign/Date
	Make	Festo	Visually/		
Vacuum			Physically		
ventury for	Model	VN-20H-T6-PQ4-	Visually/		
Carton Pick-		VQ5-RO2-M	Physically		
սթ	Qty.	01 No.	Visually/		
			Physically		
Vacuum	Make	Festo	Visually		
ventury For	Model	VN-20H-T6-PQ4-	Visually/		
Leaflet Pick		VQ5-RO2-M	Physically		
up	Qty.	01 No.	Visually/		
			Physically		
	Location	On operating panel	Visually		
	Make	Weintek	Visually/		
			Physically		
HMI	Model	MT 6070 iH 3EV	Visually/		
			Physically		
	Sr. No.	To be recorded	Visually/		
			Physically		
	Location	Inside the machine of front	Visually		
Air Pressure switch	Make	Festo	Visually/ Physically		
	Model	PEV-1/4-SC-OD	Visually/ Physically		
	Make	Rotomotive	Visually/		
			Physically		
	Model	Robus 21	Visually/		1
			Physically		
	Ratio	10:1	Visually/		
Main Gear			Physically		
box with	Voltage	380 to 415 V, 3 Ph,	Visually/		
motor		3.5 A	Physically		
motor	Rating	1.5 kW, 1400 RPM	Visually/		
			Physically		
	Sr. No.	To be recorded	Visually/		
			Physically		
Power Supply	Make	Mean well	Visually/		
			Physically		



Additional

Card for

Make

Mitsubishi

INSTALLATION QUALIFICATION FOR CARTON PACKING MACHINE

PROTOCOL No.:

			.	 1
	Model	S-150-24	Visually/	
			Physically	
	Make	Omron	Visually/	
Single Phase			Physically	 -
Preventer	Model	K8AK	Visually/	
			Physically	
	Location	Inside the control cabinet	Visually	
PLC for	Make	Mitsubishi	Visually/	
machine			Physically	
	Model	FX3G-60M	Visually/	
			Physically	
	Location	Inside the control	Visually	
	Location	cabinet	Vibuily	
	Make	Danfoss	Visually/	
	WIAKC	Damoss	Physically	
AC drive for	Model	VLT Microdrive	Visually/	
main motor	Model		-	
main motor	Dating	1.5 LW 2.0 UD	Physically Viewelly/	
	Rating	1.5 kW, 2.0 HP	Visually/	
	C N		Physically	
	Sr. No.	To be recorded	Visually/	
		T 1 1 1	Physically	
	Location	Inside the control cabinet	Visually	
	Make	Danfoss	Visually/	
			Physically	
	Model	VLT Microdrive	Visually/	
AC drive for			Physically	
conveyor	Rating	0.37 kW, 0.5 HP	Visually/	
			Physically	
	Sr. No.	To be recorded	Visually/	
			Physically	
	Make	Kubler	Visually/	
			Physically	
Encoder	Model	8.5000.835A.0360	Visually/	
		.0050	Physically	
	Make	Mitsubishi	Visually/	
	1. Lunco		Physically	
	04-1	02 No.		
Servo Motor	Qty.	02 Nos.	Visually/	
			Physically	
	Sr. No.	To be recorded	Visually/	
			Physically	
	+	1	+ +	 t

Visually/ Physically



PROTOCOL No.:

Input	Model	FX2N-8EX-ES	Visually/	
mput	Wiodel		Physically	
	Make	Mitsubishi	Visually/	
Additional	Wake	Wittsdolbin	Physically	
Card for	Model	FX2N-8EYT-ESS	Visually/	
Output	WIGGET	17210-0211-255	Physically	
	Make	Comintec	Visually/	
Carton Chain	WithKe	Commee	Physically	
Clutch	Model	1.90 DSR/ FAMS	Visually/	
Clutch	WIGGET	1.70 DSR/ 17405	Physically	
	Make	Schneider	Visually/	
	WIAKC	Semicidei	Physically	
MCB	Location	Inside the control	Visually/	
	Location	cabinet	Physically	
	Otri	03 Nos.	Visually/	
Emergency	Qty.	05 1108.		
Stop Push			Physically	
Button				
Main Switch	Location	On control cabinet	Visually	
Speed	Location	On operating panel	Visually	
Control				
Potentio-				
meter				
Pressure	Location	Inside the machine	Visually	
Regulators			5	
0		Pneumatic	Cylinders	
E	Make	Festo	Visually/	
Empty			Physically	
Carton	Model	DSN-25-50-P	Visually/	
Ejection			Physically	
	Make	Festo	Visually/	
Carton Top			Physically	
Support	Model	DNC-32-100-PPV	Visually/	
			Physically	
	Make	Festo	Visually/	
Pusher			Physically	
Diverter	Model	DSN-12-25-P	Visually/	
			Physically	
		Sens		
	[Gens		
			Visually/	
Product	Make	IFM	Technical	
level/overflow			specification	
			Visually/	
	Model	OJ5148	Technical	
			specification	
Leaflet low			Visually/	
level in	Make	IFM	Technical	
Magazine			specification	



INSTALLATION QUALIFICATION F **CARTON PACE**

PROTOCOL No.:

FOR	
KING MACHINE	

	Model	OJ5148	Visually/ Technical	
	WIGUCI	033140	specification	
			Visually/	
	Make	IFM	Technical	
	WIAKC	11 111	specification	
Leaflet Present			Visually/	
Leanet Tresent	Model	OJ5148	Technical	
	Model	033140	specification	
			Visually/	
	Make	IFM	Technical	
	WICKE		specification	
Carton Present			Visually/	
	Model	OJ5148	Technical	
	WIGUEI	033140	specification	
			Visually/	
	Make	Pepperl & Fuchs	Technical	
Carton low	WIANU		specification	
level in			Visually/	
Magazine			Technical	
	Model	NBB4-12GM50-E2		
			specification	
			Visually/	
	Make	Aake Pepperl & Fuchs	Technical	
Sucker arm			specification	
selection		odel NBB5-18GM50-E2	Visually/	
	Model		Technical	
			specification	
			Visually/	
	Make	Pepperl & Fuchs	Technical	
Hand wheel			specification	
out			Visually/	
	Model	NBB4-12GM50-E2	Technical	
			specification	
			Visually/	
	Make	Siemens	Technical	
Pusher loading			specification	
safety Switch		ID (7 (2 0E 2 100	Visually/	
-	Model	IP 67 (3 SE 3 100-	Technical	
		1E)	specification	
			Visually/	
	Make	IFM	Technical	
Empty carton			specification	
check			Visually/	
	Model	KB 5004	Technical	
			specification	
Carton chain			Visually/	
clutch	Make	Pepperl & Fuchs	Technical	
V141011	mane	r oppoint & r dons	specification	



PROTOCOL No.:

			Vienelly/	
	Model	NBB4-12GM50-E2	Visually/ Technical	
	WIOdel	NDD4-12010130-E2	specification	
			Visually/	
	Make	Telemecanique	Technical	
Guard	WIAKE	reieniecanique	specification	
switches			Visually/	
switches	Model	XCJ-110	Technical	
	WIOdel	ACJ-110	specification	
			Visually/	
	Make	IFM	Technical	
Blister low	WIAKE	11 111	specification	
level check in			Visually/	
collator	Model	OJ5148	Technical	
	WIOdel	033140	specification	
			Visually/	
	Make	Wenglor	Technical	
Blister level	Wiake	Wengion	specification	
sensing			Visually/	
sensing	Model CP70QXVT80	Technical		
	Widdel	er /oquivioo	specification	
		Alarn	_	
		Over the top of	Visually	
Tower Lamp	Location	machine on carton	Visually	
rower Lump	Location	magazine wall		
	Location	Inside the tower	Visually	
Buzzer	Location	lamp	Visually	
		Pressure	Cauga	
			U U	
Main FRL	Make	Festo	Visually	
Unit	Range	0-16 bar	Visually	
Rotary Pickup	Make	Festo	Visually	
Filter Unit	Range	0-16 bar	Visually	
Leaflet	Make	Festo	Visually	
Vacuum			X7' 11	
Ventury	Range	0-16 bar	Visually	
	1	Vacuum	Gauge	
Vacuum	Make	Piab	Visually	
Gauge for Carton	Range	-30 to 0" Hg	Visually	

Remark: -----_____



5.5 IDENTIFICATION OF SUPPORTING UTILITIES:

Utility	Method of verification	Observation	Checked by Sign/ Date
Electricity: 3 phase, 415V±10% AC, 50 Hz supply with neutral and proper earthing	Physically and with clamp meter		
Compressed air: Minimum pressure 6 bar max	Physically		

Remark: -----



5.6 IDENTIFICATION OF SAFETY FEATURES: Identify and record the safety features (if any) and their function in following tables:

Safety Features Description	Function	Method Of Verification	Observation	Checked By Sign/ Date
Earthing	To avoid electrical shocks due to leakage current	Physically		
Emergency stop button	To stop machine immediately in case of emergency	Physically		
Safety around the machine	All moving parts of the machine are covered by guards to prevent accidents	Physically		
Machine electrical panel	Corresponding MCB trips immediately in case of overload	Physically		
Limit switch	If door open during operation the machine should be stopped	Physically		
Interlocking with electrical supply	Machine stops in case of single phasing & cannot be restarted until 3 phase supply is restored	Physically		

Remark: -----



5.7 IDENTIFICATION OF STANDARD OPERATING PROCEDURE (SOP)

The following Standard Operating Procedures were identified as important for effective performance of Carton packing machine.

S.No.	SOP TITLE	IDENTIFIED BY	DATE

Remark: -----



5.8 IDENTIFICATION OF COMPONENT TO BE CALIBRATED

Name of Components	Range	Make	ID	Location	Identified By Sign/Date

Remark: -----

Reviewed by (Sign/Date)



5.9 VERIFICATION OF DRAWING AND DOCUMENTS:

Following documents are reviewed and attached as listed below:

S.No.	DRAWING AND DOCUMENT DETAIL	CHECKED BY (SIGN)	DATE

Remark: -----



5.10 LIST OF ANNEXURES:

Annexure No.	Document Title

Remarks (if any):

Done By & Date:

Verified By & Date:



5.11 DEFICIENCY AND CORRECTIVE ACTION (S) REPORT (S)

Following deficiency was verified and corrective actions taken in consultation with the Engineering Department.

Description of deficiency:

Corrective action(s) **taken:**

Deviation accepted by (Sign/Date)

Deviation Approved by (Sign/Date)



ARREVIATIONS 5.12

5.12	ARREA	

- : Voltage V
- : Alternate Current AC
- PLC : Programmable Logic Controller
- Hz : Hertz
- RPM : Revolution per Minute
- HMI : Human Machine Interface
- Max. : Maximum
- : Ampere А
- kW : Kilowatt
- CP : Carton Packing



6.0 INSTALLATION QUALIFICATION FINAL REPORT:

6.1 SUMMARY:

6.2 CONCLUSION:

Prepared By Sign/Date Checked By Sign/Date



6.3 FINAL REPORT APPROVAL

It has been verified that all tests required by this protocol are completed, reconciled and attached to this protocol or included in the qualification summary report. Verified that all amendments and discrepancies are documented, approved and attached to this protocol. If applicable, signature in the block below indicates that all items in this qualification report of Automatic cartoning machine have been reviewed and found to be acceptable and that all variations or discrepancies have been satisfactorily resolved.

FUNCTION	NAME	DESIGNATION	DEPARTMENT	SIGNATURE	DATE
REVIEWED BY			QUALITY ASSURANCE		
			ENGINEERING		
			PRODUCTION		
APPROVED BY			HEAD OPERATION		
			QUALITY ASSURANCE		