

QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

**PAGE No.: 1 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

System Name	Automatic Rotary Vacuumatric Dry Syrup Filling With ROPP Capping Machine		
System ID			
Location	Dry Syrup		
Effective Date			



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
• • • • • • • • • • • • • • • • • • • •
REVISION No: 00
<b>EFFECTIVE DATE:</b>

PAGE No.: 2 of 63

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### **CONTENTS**

1.0.0	PRE APPROVAL SIGNATURES:	3
2.0.0	GENERAL:	4
2.1.0	PURPOSE:	4
2.2.0		
2.3.0	BACKGROUND:	4
2.4.0	REVISION HISTORY:	4
2.5.0		
2.6.0		
2.7.0		
2.8.0	TRAINING RECORD:	7
2.9.0	PLC DESCRIPTION:	8
2.10.	0 SYSTEM DESCRIPTI <mark>ON</mark>	9
2.11.	0 PLC SYSTEM SCHEMATIC DIAGRAM	10
3.0.0	OPERATIONAL QUALIFICATION TEST	11
2.0.0		
3.1.0	VERIFICATION OF MASTER TEST INSTRUMENTS	12
3.2.0		14
3.3.0		
3.4.0		
3.5.0		
3.6.0	VERIFICATION OF SECURITY LEVELS	27
3.7.0	VERIFICATION OF HMI SCREENS	33
3.8.0	VERIFICATION OF RANGE OF SET PARAMETERS	37
3.9.0	VERIFICATION OF POWER LOSS RECOVERY CONDITION	42
3.10.	0 VERIFICATION OF COMMUNICATION FAILS RECOVERY CONDITION	46
3.11.	0 VERIFICATION OF ALARMS AND INTERLOCKS	50
3.12.	0 VERIFICATION AND RECORD AN INTEGRATED CONTROL LOOP TEST	55
4.0.0	DEVIATION REPORT AND DISCREPANCY REPORT	58
5.0.0	SUMMARY REPORT	59
6.0.0	TERMINOLOGIES	60
7.0.0	LIST OF ATTACHMENTS	61
7.000		VI
8.0.0	LIST OF ABBREVIATIONS	62
9.0.0	POST APPROVAL SIGNATURES	63



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 3 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 1.0.0 PRE APPROVAL SIGNATURES:

The signatures below indicate pre approval of this operational qualification document and it is ready for execution. Any changes or modifications to the intent or the acceptance criteria of this operational qualification document, following approval, requires the generation of an amendment which must be approval prior to execution.

#### OPERATIONAL QUALIFICATION PRE APPROVAL

Name	Department	Designation	Signature/Date
	OF THE		
	Engineering		
	<b>U U</b>		
	Engineering		
	Production		
	Quality		
		Engineering  Engineering  Production	Engineering  Engineering  Production  Quality

**Final Approval:** Final approval has been given by the following

Function	Name	Designation	Signature/Date
Approved by		Head Quality Assurance	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 4 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### **2.0.0 GENERAL:**

#### 2.1.0 **PURPOSE**:

The purpose of this operational qualification document is to verify and document that the PLC system of "Automatic Rotary Vacuumatric Dry Syrup Filling with ROPP Capping Machine" has been operated and fulfill its intended use when placed in its intended environment.

The purpose of the Operational Qualification is to provide documented evidence to demonstrate that the PLC system is operated and performed as per the manufacturer specifications.

#### 2.2.0 SCOPE:

This Operational Qualification will be performed on "Automatic Rotary Vacuumatric Dry Syrup Filling With ROPP Capping Machine" which is located in "Dry Syrup-1".

This operational qualification document describes the PLC system hardware and software, equipment details, test procedures, documentation, references and acceptance criteria used to establish that "Wash Area" has been operated in accordance with the master documentations.

#### 2.3.0 BACKGROUND:

#### 2.4.0 <u>REVISION HISTORY:</u>

Version No.	Effective Date	Reason for Change
00		New Document



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>
DACEN F. C.C.

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 2.5.0 **REFERENCES**:

The test and execution procedure within the scope of the qualification document are consistence with the following reference.

Guideline	<u>Details</u>	
GAMP-5	Good Automated Manufacturing Practices	
21 CFR Part 210	Code of Federal Regulations, Current Good Manufacturing Practices in Manufacturing Processing, Packing.	
21 CFR Part 211	Code of Federal Regulations, Current Good Manufacturing Practices for finished Pharmaceuticals.	
EU GMP Annex-11	European Union Good Manufacturing Practices Annexure-11	

#### 2.6.0 **VALIDATION TEAM:**

Validation team is responsible for the execution of operational qualification of PLC system. Validation team comprises.

Name	Department	Designation	Sign & Date
	Engineering		
	Production		
	QA		



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.:** 6 of 63

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 2.7.0 **RESPONSIBILITY:**

- ➤ Collect all manuals, electrical wiring diagram and documentary or any other data necessary for the preparation, execution of operational qualification document from M/S......
- > Preparation and execution of Operational Qualification document.
- ➤ Initiate Qualification study in coordination with Production, Quality Assurance and Engineering.
- Provide training to the persons, who present during execution, of this study.

En	gineering	Pro	oduction	Qι	uality Assurance
>	Co-ordinate during execution of Qualification activities.	>	Co-ordinate during execution of Qualification activities.	>	Co-ordinate during execution of Qualification activities.
<b>A</b>	To provide utilities for Qualification activity.	>	Provide personnel for facilitating the execution of Qualification activity.		To review and approve the Qualification document.
<b>A</b>	To review the operational qualification document.	>	Check that test requirements  To Review the operational qualification document.		



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
<b>REVISION No: 00</b>	
<b>EFFECTIVE DATE:</b>	

**PAGE No.: 7 of 63** 

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QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00
EFFECTIVE DATE:

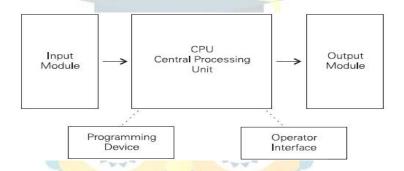
**PAGE No.: 8 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 2.9.0 PLC DESCRIPTION:

The dictionary defines automation as "the creation and application of technology to monitor and control the production and delivery of products and services."

"Programming Logic Controller" (PLC) is an industrial computer control system that continuously monitors the state of input devices and makes decisions based upon a custom program, to control the state of devices connected as outputs.



PLC consists of input modules or points, a Central Processing Unit (CPU), and output modules or points. An input accepts a variety of digital or analog signals from various field devices (sensors) and converts them into a logic signal that can be used by the CPU. The CPU makes decisions and executes control instructions based on program instructions in memory.

Output modules convert control instructions from the CPU into a digital or analog signal that can be used to control various field devices (actuators). A programming device is used to input the desired instructions. These instructions determine what the PLC will do for a specific input. An operator interface device allows process information to be displayed and new control parameters to be entered.

The PLC is used many inputs or modules to sense and measure physical quantities of equipment, such as motion, temperature, level, current, voltage, position, and pressure etc. Depending on the status of inputs which sensed by inputs or modules, processor controls various output module to energize or drive the field devices such as valves, motor starters and contactors etc that apply power circuit voltages to the control devices.



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
• • • • • • • • • • • • • • • • • • • •
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 9 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

Digital or discrete input/output has only two states, one is ON and another is OFF. Input and output have light emitting diode (LED) to indicate the state of each input/output. Analog input/output allow to monitor and controlling analog voltage and control.

"Human Machine Interface" (HMI) is platform which is assist the operator to supervise and control the equipment. Operator has displayed information from the HMI and gives the command to PLC then PLC will execute the command.

#### 2.10.0 SYSTEM DESCRIPTION

The PLC Based control system should have capability to control Automatic Rotary Vacuumatric Dry syrup Filling With ROPP Capping Machine. Purpose of the PLC system is to monitor, operate and control the machine. PLC System gets Digital Signal from Field devices like No Bottle, Dose, No Cap, No Bottle No Cap, Inching, Spindle Jam, Emergency, Pursing, Low Air, Low Vacuum, Powder Level Low. The data is processed in CPU of PLC and give Output as per the logics of Main Motor, Conveyor 1, Vibrator Motor, Vacuum Pump, Dose Valve, No Cap Valve, Pursing Valve, Cap Feeder, Conveyor 2.



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No. 00	

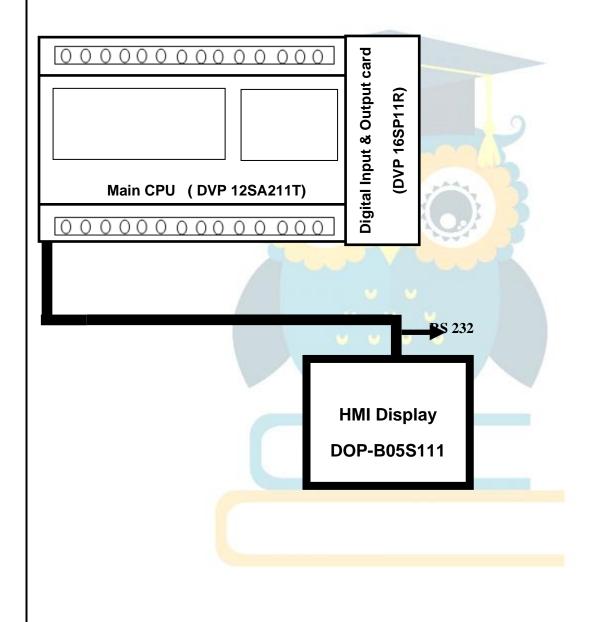
**PAGE No.: 10 of 63** 

**EFFECTIVE DATE:** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 2.11.0 PLC SYSTEM SCHEMATIC DIAGRAM

The PLC system schematic diagram for the "Automatic Rotary Vacuumatric Dry Syrup Filling With ROPP Capping Machine" automation is given below:





QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 11 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.0.0 OPERATIONAL QUALIFICATION TEST

Sr. No.	<u>Test Details</u>			
1	VERIFICATION OF MASTER TEST INSTRUMENTS			
2	VERIFICATION OF CALIBRATION CERTIFICATES OF FIELD INSTRUMENTS			
3	VERIFICATION OF MAINTENANCE QUALIFICATION DOCUMENTS			
4	VERIFICATION OF LED INDICATION OF PLC SYSTEM			
5	VERIFICATION OF PLC INPUTS/ OUTPUTS			
6	VERIFICATION OF HMI SCREENS			
7	VERIFICATION THE RANGE OF SET PARAMETERS			
8	VERIFICATION AND TESTING OF POWER LOSS RECOVERY CONDITION			
9	VERIFICATION OF COMMUNICATION FAILS RECOVERY CONDITION			
10	VERIFICATION OF ALARMS AND INTERLOCKS			
11	VERIFICATION OF INTEGRATED CONTROL LOOP			



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00
<b>EFFECTIVE DATE:</b>

PAGE No.: 12 of 63

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.1.0 <u>VERIFICATION OF MASTER TEST INSTRUMENTS</u>

**Purpose**: This test is verified to master instrument which is used for testing.

**Scope** : Recording of master test instrument name, ID no and calibration date and due

date.

Instrument Name - Instrument Tag Plate

➤ Instrument ID No - Instrument Tag Plate

➤ Calibration date and Due date – Calibration Certificate

**Discrepancy**: If any discrepancy is encountered which prevent completion of the report as

originally intended, document the discrepancy report.

Acceptance : Recorded data from manufacturer tag plates and master instruments should be

Criteria calibrated.



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	

REVISION No: 00
EFFECTIVE DATE:

PAGE No.: 13 of 63

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.1.1 DATA TABLE OF MASTER TEST INSTRUMENTS

Sr. No	Instrument Name	Instrument ID /Make /Model	Calibration Date	Calibration Due Date	Meets acceptance criteria:	Sign. & date
1					Yes () No ()	
2				4	Yes () No ()	

Comments/ Remarks:	

Function	Name	Department	Sign. & Date
Tested by		Engineering	
Verified by		Engineering	
Reviewed by		QA	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 14 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.2.0 VERIFICATION OF CALIBRATION CERTIFICATES OF SENSORS

**Purpose** : Verify the calibration certificates of critical sensors in PLC system.

**Scope** : Verify and record all the details of critical sensors.

**Procedure**: > Check the availability of calibration certificates of critical sensors.

Check & record the sensor name and ID number which connected PLC system.

Record the calibration certificate's details of critical sensors.

Discrepancy: If any discrepancy is encountered which prevent completion of the report as

originally intended, document the discrepancy report.

**Acceptance** : All critical sensors of PLC system must be calibrated.

Criteria



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 15 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.2.1 DATA TABLE OF CALIBRATION CERTIFICATES OF SENSORS

Sr. No.	Sensor Name	Sensor ID No	Calibration Date	Calibration Due Date	Sign. & date
	0		2		
			TI		
	\$		1/2		
		10 V 10			
		0 0 0			
		<del>\ \ \ \ \ \ \ \</del>			



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

PAGE No.: 16 of 63

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Function	Name	Department	Sign. & Date
Tested by	2	Engineering	
Verified by		Engineering	
Reviewed by	- Lu	QA	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00

**PAGE No.: 17 of 63** 

**EFFECTIVE DATE:** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.3.0 VERIFICATION OF MAINTENANCE QUALIFICATION DOCUMENTS

**Purpose**: Verify and review the documents of maintenance.

**Scope** : Verify and record the maintenance qualification document.

**Procedure** : > Check the availability of documents.

> Check the every entry for equipment maintenance is listed in log-book.

**Discrepancy**: If any Discrepancy is encountered which prevent completion of the report as

originally intended, document the Discrepancy Report.

Acceptance : All documents should available and maintain.

Criteria



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00

PAGE No.: 18 of 63

**EFFECTIVE DATE:** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.3.1 DATA TABLE OF MAINTENANCE QUALIFICATION DOCUMENTS

Sr. No	Document	Document Available (Yes/ No)	Meet Acceptance Criteria	Sign. & Date
1	Preventive Maintenance Card		Yes () No ()	
2	Log book of Equipment		Yes ( ) No ( )	

Comments/ Remarks:		
	0 0 0 0	

Function	Name	Department	Sign. & Date
Tested by		Engineering	
Verified by		Engineering	
Reviewed by		QA	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
EFFECTIVE DATE.

**PAGE No.: 19 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.4.0 VERIFICATION OF LED INDICATIONS OF PLC SYSTEM

**Purpose**: To verify LED indications of PLC system.

**Scope** : To check and recordof LED Indications of PLC system

**Procedure** : > Switch "ON" the main power supply of PLC panel

Check and record the behavior of LED in PLC system

**Discrepancy**: If any Discrepancy is encountered which prevent completion of the report as

originally intended, document the Discrepancy Report.

Acceptance

Criteria

: All LED indications of PLC system must have been properly visualized,

checked and should be same as the expected results.



QUALITY ASSURANCE DEPARTMENT

PRO	TOCOL No.:
•••••	• • • • • • • • • • • • • • • • • • • •
REV	ISION No: 00
EFF	ECTIVE DATE:

**PAGE No.: 20 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.4.1 DATA TABLE OF PLC SYSTEM LED INDICATION IN OFF CONDITION

LED	Expected state of LED	Actual state of LED	Meets acceptance criteria	Sign.& date
	PLC PR	OCESSOR (DVP-12SA	A211T)	
Power	OFF		Yes () No ()	
Run	OFF		Yes () No ()	
Error	OFF		Yes() No()	
Comm 1	OFF		Yes () No ()	

#### 3.4.2 DATA TABLE OF PLC SYSTEM LED INDICATION IN ON CONDITION

LED	Expected state of LED	Actual state of LED	M <mark>eet</mark> s acceptance criteria	Sign.& date
	PLC PR	ROCESSOR (DVP-12SA	211T)	
Power	ON	V V	Yes () No ()	
Run	ON	U U U U	Yes () No ()	
Error	OFF		Yes () No ()	
Comm 1	Blink		Yes () No ()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
••••	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

PAGE No.: 21 of 63

Function Name Department Sign. & Date Tested by Engineering Verified by Engineering Reviewed by QA	Tested by Engineering  Verified by Engineering  Reviewed by QA	Tested by Engineering  Verified by Engineering  Reviewed by QA				
Tested by Engineering  Verified by Engineering  Reviewed by QA	Tested by Engineering  Verified by Engineering  Reviewed by QA	Tested by Engineering  Verified by Engineering  Reviewed by QA				
Tested by  Engineering  Verified by  Reviewed by  QA	Tested by  Engineering  Verified by  Reviewed by  QA	Tested by  Engineering  Verified by  Reviewed by  QA				
Tested by Engineering  Verified by Engineering  Reviewed by QA	Tested by Engineering  Verified by Engineering  Reviewed by QA	Tested by Engineering  Verified by Engineering  Reviewed by QA		e		
Verified by Engineering  Reviewed by QA	Verified by Engineering  Reviewed by QA	Verified by Engineering  Reviewed by QA	Function	Name	<b>Department</b>	Sign. & Date
Verified by Engineering  Reviewed by QA	Verified by Engineering  Reviewed by QA	Verified by Engineering  Reviewed by QA	Tested by		A COLA COLA	
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QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 22 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.5.0 **VERIFICATION OF PLC INPUTS/ OUTPUTS**

**Purpose**: Verify the entire inputs/outputs of the PLC system, checking the connections to the

cards of the PLC system.

**Scope** : To check and recordthe function of all PLC Inputs and Outputs.

**Procedure**: Digital Inputs > Trigger/Force each given digital input from system.

Verify and record the status of digital inputs LED indication in PLC system and same time verify the PLC

logics in PLC software.

Digital Outputs Force each digital output ON/OFF.

Verify and record the status of digital outputs LED indication in PLC system and same time verify the PLC

logics in PLC software.

Analog Inputs Feed 4-20mA current or appropriate Ohms signal to PLC

system using calibrated Universal Calibrator.

(If Applicable) Simultaneously check the reading in PLC.

Verify and record the reading of it.

Analog Output > Measure appropriate current signal from output terminal

of PLC system using calibrated universal calibrator. (If Applicable)

Verify and record the reading of it.



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
DELICATION AS
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 23 of 63** 

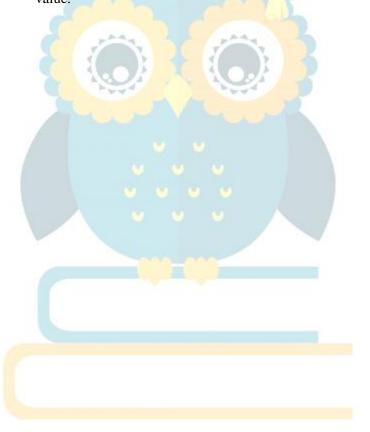
## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

**Discrepancy** 

: If any discrepancy is encountered which prevent completion of the report as originally intended, document the discrepancy report.

#### Acceptance Criteria

- : > All inputs and outputs must be verified to meet wiring diagram of PLC system and function as per design document.
  - ➤ All analog inputs/outputs range must be verified to meet calibration certificates of individual device.
  - ➤ Verification of all analog inputs/ outputs range should be within 2% of set value.





QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 24 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.5.1 DATA TABLE OF PLC DIGITAL INPUTS

		PLC Digital Input (	(DVP 12SA211T)		
PLC Address	Description	Expected state of LED	Actual state of LED	Meets acceptance criteria	Sign. & date
V0	No Doule	ON		Yes () No ()	
X0	No Bottle	OFF		Yes ( ) No ( )	
37.1	D	ON		Yes () No ()	
X1	Dose	OFF		Yes () No ()	
W2	N. C.	ON		Yes ( ) No ( )	
X2	No Cap	OFF	A aa	Yes () No ()	
W2	N P 41 N C	ON		Yes () No ()	
X3	No Bottle No Cap	OFF		Yes () No ()	
37.4	No Bottle No Cap	ON	I I CONT	Yes () No ()	
X4	Gap	OFF		Yes () No ()	
X5 Inching		ON		Yes () No ()	
	OFF	y	Yes ( ) No ( )		
<b>X</b> Y.c		ON		Yes () No ()	
X6	Spindle Jam	OFF	U	Yes () No ()	
377	P	ON		Yes () No ()	
X7	Emergency	OFF		Yes () No ()	
		PLC Digital Input	(DVP 16SP11R)		
		ON		Yes() No()	
X20	Pursing	OFF		Yes() No()	
***		ON		Yes () No ()	
X21 Low Air	OFF		Yes() No()		
		ON		Yes () No ()	
X22	Low Vacuum	OFF		Yes () No ()	
1100		ON		Yes () No ()	
X23	Powder Level Low	OFF		Yes () No ()	



X24 to

Y25 to

Y27

Spare

## PHARMA SCHOLARS

QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No: 00	

**PAGE No.: 25 of 63** 

Yes () No ()

**EFFECTIVE DATE:** 

#### OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

		PLC Digital Outputs	s (DVP 12SA211T)		
PLC Address	Description	Expected state of LED	Actual state of LED	Meets acceptance criteria	Sign. & date
Y0	Main Matan	ON		Yes () No ()	
10	Main Motor	OFF		Yes () No ()	
X71	G 1	ON		Yes () No ()	
Y1	Conveyor-1	OFF	400/1	Yes () No ()	
***	***	ON		Yes () No ()	
Y2	Vibrator Motor	OFF		Yes () No ()	
		ON	A VOSA	Yes () No ()	
Y3	Vacuum Pump	OFF		Yes () No ()	
		PLC Digital Output	s (DVP 16SP11R)		
***		ON	٧	Yes () No ()	
Y20	Dose Valve	OFF	0 0	Yes () No ()	
		ON	A	Yes () No ()	
Y21	No Cap Valve	OFF		Yes () No ()	
		ON	0	Yes () No ()	
Y22	Pursing Valve	OFF		Yes () No ()	
		ON		Yes () No ()	
Y23	Cap Feeder	OFF		Yes() No()	
		ON		Yes () No ()	
Y24	Conveyor-2	OFF		Yes () No ()	

NA



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
<b>REVISION No: 00</b>	
<b>EFFECTIVE DATE:</b>	

PAGE No.: 26 of 63

Function	Name	Department	Sign. & Date
Tested by		Engineering	
Verified by		<b>E</b> ngineering	
Reviewed by		QA	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
REVISION No: 00	
EFFECTIVE DATE.	

**PAGE No.: 27 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.6.0 <u>VERIFICATION OF SECURITY LEVELS</u>

Purpose : Verify and testing of different security levels to prevent the unauthorized user

access.

**Scope** : Verify and record the user access to PLC.

**Procedure** : > Switch ON the PLC.

➤ Challenge all the parameters with entering different level user passwords.

Record the warning messages from PLC (if any).

**Discrepancy**: If any Discrepancy is encountered which prevent completion of the report as

originally intended, document the Discrepancy Report.

Acceptance

Criteria

System must prevent the unauthorized users. Access Rights should be limited to

particular level as per configured.



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 28 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.6.1 DATA TABLE OF PLC ACCESS

Procedure	<b>Expected result</b>	Actual result	Meets acceptance criteria	Sign. & date
	LEVE	L-0 (Operator)		
Attempt to gain access with an incorrect combination of user name and password for operator levels	User should not able to access the system		Yes () No ()	
Attempt to gain access with a correct combination of user name and password for operator levels	User should able to access the system		Yes () No ()	
	LEVEI	L-5 (Supervisor)		
Attempt to gain access with an incorrect combination of user name and password for supervisor levels	User should not able to access the system		Yes() No()	
Attempt to gain access with a correct combination of user name and password for supervisor levels	User should able to access the system		Yes () No ()	
	LEVE	L-6 (Manager)		
Attempt to gain access with an incorrect combination of user name and password for Admin levels	User should not able to access the system	V V V	Yes () No ()	
Attempt to gain access with a correct combination of user name and password for Admin levels	User should able to access the system	10-000	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

PAGE No.: 29 of 63

Procedure	<b>Expected result</b>	Actual result	Meets acceptance criteria	Sign. & date
	LEVI	EL-7 (Admin)		
Attempt to gain access with an incorrect combination of user name and password for Manager levels	User should not able to access the system		Yes () No ()	
Attempt to gain access with a correct combination of user name and password for Manager levels	User should able to access the system		Yes () No ()	





QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00

**EFFECTIVE DATE:** 

**PAGE No.: 30 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.6.2 DATA TABLE OF FUNCTION CONFIGURATION

Functions		Lev	el		Meets acceptance criteria	Sign. & date
	0	5	6	7		
Auto Mode					Yes () No ()	





QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
EFFECTIVE DATE:
PAGE No.: 31 of 63

Manual Mode							
Product Counter    Product Counter   Product Cou	Manual Mode					Yes () No ()	
Fault Display	Recipe Setting					Yes () No ()	
Timer Setting Screen	Product Counter					Yes () No ()	
Input Status Screen  Output Status Screen  Wes () No ()  Yes () No ()  Machine Parameter Screen  Wes () No ()  Yes () No ()  Yes () No ()	Fault Display					Yes () No ()	
Output Status Screen    Output Status Screen   Yes () No ()    Machine Parameter Screen   Yes () No ()    Machine Parameter Setting Screen   Yes () No ()	Timer Setting Screen					Yes () No ()	
Machine Parameter Screen    Yes() No()    Machine Parameter Setting Screen	Input Status Screen				0	Yes () No ()	
Machine Parameter Setting Screen	Output Status Screen	G.			Ö	Yes () No ()	
Wachine Farameter Setting Screen	Machine Parameter Screen		0			Yes () No ()	
	Machine Parameter Setting Screen		_°	o O		Yes () No ()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

**PAGE No.: 32 of 63** 

Function	Name	<b>Department</b>	Sign. & Date
Tested by	Traine .	Engineering	Sign. & Date
Verified by	100	Engineering	
Reviewed by		QA	
		0 0 0	J



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 33 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.7.0 <u>VERIFICATION OF HMI SCREENS</u>

**Purpose**: To verify each function of HMI screens, function keys.

**Scope** : Verify and record all HMI screens and function keys.

Procedure

- Take program backup of HMI and verify with the actual function screens.
  - ➤ If backup not possible then take screens from manual and verify with the actual function screens.
  - Check all programmable function keys for their actual response in each screen. Record the results.
  - Check Function Key Command are properly programmed by operating output devices.
- ➤ Verify the display on HMI with actual machine conditions and record the actual results.
- Open a screen; check values displayed on HMI for each display object.
  Record observations.

**Discrepancy** 

: If any discrepancy is encountered which prevent completion of the report as originally intended, document the discrepancy report.

Acceptance

All programmable keys and displays should perform as per define function

Criteria



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
REVISION No: 00	
EFFECTIVE DATE:	

**PAGE No.: 34 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.7.1 DATATABLE OF HMI SCREENS

Sr. No.	Screen Name	Available Yes/No	Meets acceptance criteria	Sign. & date
01	Welcome Screen		Yes ( ) No ( )	
02	Run Mode Screen		Yes () No ()	
03	Manual Mode Screen		Yes ( ) No ( )	
04	Speed Setting Screen		Yes ( ) No ( )	
05	Product Counter Screen		Yes () No ()	
06	Login Screen		Yes () No ()	
07	Fault Display Screen	-	Yes () No ()	
08	Timer Setting Screen		Yes () No ()	
09	Input Status Screen		Yes () No ()	
10	Output Status Screen		Yes () No ()	
11	Machine Parameter Screen	y	Yes () No ()	
12	Machine Parameter Setting Screen	v /	Yes () No ()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

PAGE No.: 35 of 63

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.7.2 DATATABLE OF HMI DISPLAY

Parameter	Span	Actual Result	Meet Acceptance Criteria	Sign. & Date	
Run Mode Screen					
VIB. Motor	0.0 to 50.0		Yes ( ) No ( )		
Counter	Numeric		Yes ( ) No ( )		
Manual Mode Screen					
Main Motor Stop	0.0 to 120.0		Yes () No ()		
Conveyor 1 Stop	0.0 to 50.0		Yes () No ()		
VIB. Motor Stop	0.0 to 50.0		Yes () No ()		
Conveyor 2 Stop	0.0 to 60.0	Jane	Yes() No()		
<b>Speed Setting Screen</b>			5		
Main Motor (BPM)	0.0 to 120.0		Yes () No ()		
Conveyor 1 H.Z	0.0 to 120.0		Yes () No ()		
Conveyor 2 H.Z	0.0 to 120.0	0 0	Yes ( ) No ( )		
Main Motor (BPM)	0.0 to 120.0		Yes () No ()		
Conveyor 1 H.Z	0 to 50	<b>U</b>	Yes ( ) No ( )		
Conveyor 2 H.Z	0 to 50	Laur	Yes () No ()		
Recipe	0 to 50		Yes () No ()		
<b>Product Counter Screen</b>					
Counter	Numeric		Yes() No()		



QUALITY ASSURANCE DEPARTMENT

	PROTOCOL No.:
	REVISION No: 00
İ	EFFECTIVE DATE:

PAGE No.: 36 of 63

Parameter	Span	Actual Result	Meet Acceptance Criteria	Sign. & Date
<b>Timer Setting Screen</b>				
No Bottle ON TMR	0.0 to 99.9		Yes ( ) No ( )	
No Bottle OFF TMR	0.0 to 99.9		Yes () No ()	
NO Cap ON TMR	0.0 to 99.9		Yes () No ()	
NO Cap OFF TMR	0.0 to 99.9		Yes () No ()	
Dossing TMR	0.000 to 9.999		Yes () No ()	
Purzing ON Delay Time	0.00 to 99.99		Yes () No ()	
Purzing OFF Delay Time	0.00 to 99.99		Yes() No()	
Powder Level ON TMR	0.00 to 99.99		Yes() No()	

Comments/ Remarks:	

Function	Name	Department	Sign. & Date
Tested by		Engineering	
Verified by		Engineering	
Reviewed by		QA	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

**PAGE No.: 37 of 63** 

# OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.8.0 VERIFICATION OF RANGE OF SET PARAMETERS

**Purpose**: To check and verify the range of set parameters in HMI screens.

**Scope** : Verify and record the minimum and maximum values of set parameter.

**Procedure** : > Enter minimum value for the given span and record it.

Enter maximum value for the given span and record it.

Enter value above and below the acceptable span and observe the response.

➤ If value cannot be entered "above" maximum and "below" minimum then record the message as "Value cannot be entered".

**Discrepancy**: If any discrepancy is encountered which prevent completion of the report as

originally intended, document the discrepancy report.

**Discrepancy**: If any discrepancy is encountered which prevent completion of the report as

originally intended, document the discrepancy report.

Acceptance : All programmable keys and displays should perform as per define function

Criteria



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No. 00

**EFFECTIVE DATE:** 

**PAGE No.: 38 of 63** 

Parameter	Span	Min span	Value is set in system	Max span	Value is set in system	Below Range setting	Value is not set in system	Upper Range setting	Value is not set in system	Meet Acceptanc e Criteria	Sign. & Date
Run Mode Scr	een										
VIB. Motor	0.0 to 50.0		Yes () No ()	8	Yes () No ()		Yes() No()		Yes () No ()	Yes () No ()	
Manual Mode	Screen			3			R				-
Main Motor Stop	0.0 to 120.0		Yes () No ()		Yes () No ()	v	Yes() No()		Yes() No()	Yes () No ()	
Conveyor 1 Stop	0.0 to 50.0		Yes () No ()		Yes () No ()	U U	Yes() No()		Yes() No()	Yes () No ()	
VIB. Motor Stop	0.0 to 50.0		Yes () No ()		Yes() No()		Yes() No()		Yes() No()	Yes() No()	
Conveyor 2 Stop	0.0 to 60.0		Yes() No()		Yes() No()		Yes () No ()		Yes() No()	Yes () No ()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

PAGE No.: 39 of 63

Parameter	Span	Min span	Value is set in system	Max Span	Value is set in system	Below Range setting	Value is not set in system	Upper Range setting	Value is not set in system	Meet Acceptanc e Criteria	Sign. & Date
Speed Setting S	Screen			0			9				
Main Motor (BPM)	0.0 to 120.0		Yes () No ()	8	Yes() No()	200	Yes ()		Yes() No()	Yes() No()	
Conveyor 1 H.Z	0.0 to 120.0		Yes() No()		Yes() No()		Yes () No ()		Yes () No ()	Yes() No()	
Conveyor 2 H.Z	0.0 to 120.0		Yes () No ()	T	Yes() No()	A. C.	Yes () No ()		Yes() No()	Yes() No()	
Main Motor (BPM)	0.0 to 120.0		Yes () No ()		Yes() No()	V	Yes () No ()		Yes () No ()	Yes() No()	
Conveyor 1 H.Z	0 to 50		Yes () No ()		Yes() No()	U U	Yes () No ()		Yes() No()	Yes() No()	
Conveyor 2 H.Z	0 to 50		Yes () No ()		Yes() No()		Yes () No ()		Yes() No()	Yes() No()	
Recipe	0 to 50		Yes () No ()		Yes() No()		Yes() No()		Yes() No()	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 40 of 63** 

Parameter	Span	Min span	Value is set in system	Max span	Value is set in system	Below Range setting	Value is not set in system	Upper Range setting	Value is not set in system	Meet Acceptanc e Criteria	Sign. & Date
Timer Setting Se	creen			C			2				
No Bottle ON TMR	0.0 to 99.9		Yes() No()		Yes() No()	200	Yes() No()		Yes() No()	Yes() No()	
No Bottle OFF TMR	0.0 to 99.9		Yes () No ()		Yes () No ()		Yes () No ()		Yes () No ()	Yes() No()	
NO Cap ON TMR	0.0 to 99.9		Yes () No ()	X	Yes () No ()	A.	Yes () No ()		Yes () No ()	Yes() No()	
NO Cap OFF TMR	0.0 to 99.9		Yes () No ()		Yes () No ()	V	Yes () No ()		Yes () No ()	Yes() No()	
Dossing TMR	0.000 to 9.999		Yes () No ()		Yes() No()	U U	Yes () No ()		Yes () No ()	Yes() No()	
Purzing ON Delay Time	0.00 to 99.99		Yes () No ()		Yes() No()	~~~	Yes () No ()		Yes () No ()	Yes() No()	
Purzing OFF Delay Time	0.00 to 99.99		Yes() No()		Yes() No()		Yes () No ()		Yes () No ()	Yes() No()	
Powder Level ON TMR	0.00 to 99.99		Yes() No()		Yes () No ()		Yes () No ()		Yes () No ()	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

	PROTOCOL No.:
=	REVISION No: 00
	EFFECTIVE DATE:

PAGE No.: 41 of 63

Function Name Department Sign. & I Tested by Engineering  Verified by QA				
Tested by Engineering  Verified by Engineering  Reviewed by QA				
Tested by  Engineering  Verified by  Reviewed by  QA				
Tested by  Engineering  Verified by  Reviewed by  QA				
Verified by Engineering  Reviewed by QA	Function	Name	<b>D</b> epartment	Sign. & Date
Verified by Engineering  Reviewed by QA	Tested by		A U A A A	
	Verified by			
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QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
• • • • • • • • • • • • • • • • • • • •
<b>REVISION No: 00</b>
<b>EFFECTIVE DATE:</b>

**PAGE No.: 42 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.9.0 VERIFICATION OF POWER LOSS RECOVERY CONDITION

**Purpose**: Verify and testing of power loss recovery condition.

**Scope** : Record value of process set-parameters after the power fails.

**Procedure** : > Switch "ON" the PLC system.

Enter value in set parameter field in HMI screen and record it.

Start the machine.

Cut power supply during machine is in "ON" condition.

Restore power supply after 240 seconds.

Restart the machine and again record the value which is entered before.

Ensure that machine should not start unless and until start command is given.

**Discrepancy** 

: If any Discrepancy is encountered which prevent completion of the report as originally intended, document the Discrepancy Report.

Acceptance

After Power restore the value of process set-parameter should not changed.

Criteria

The process time should start from previous value when the power loss.

The machine should not start without command by user when power failure condition occurs.

Machine works normally after Power loss recovery condition.



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
• • • • • • • • • • • • • • • • • • • •	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

PAGE No.: 43 of 63

# OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARYS VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.9.1 DATA TABLE OF POWER LOSS RECOVERY CONDITION

Parameter Description	Value Before power loss	Value after power recovery	Expected Result	Meets acceptance criteria	Sign. & date
Run Mode Screer	1				
VIB. Motor			Value remains same	Yes () No ()	
Manual Mode Sci	reen				
Main Motor Stop	C		Value remains same	Yes() No()	
Conveyor 1 Stop	9		Value remains same	Yes() No()	
VIB. Motor Stop	*		Value remains same	Yes () No ()	
Conveyor 2 Stop	9		Value remains same	Yes () No ()	
<b>Speed Setting Scr</b>	een				
Main Motor (BPM)		٧	Value remains same	Yes() No()	
Conveyor 1 H.Z			Value remains same	Yes() No()	
Conveyor 2 H.Z			Value remains same	Yes () No ()	
Main Motor (BPM)			Value remains same	Yes () No ()	
Conveyor 1 H.Z			Value remains same	Yes () No ()	
Conveyor 2 H.Z			Value remains same	Yes () No ()	
Recipe			Value remains same	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
REVISION No: 00	
EFFECTIVE DATE:	

**PAGE No.: 44 of 63** 

Parameter Description	Value Before power loss	Value after power recovery	Expected Result	Meets acceptance criteria	Sign. & date
Гimer Setting Sc	reen	1	1	11	
No Bottle ON ΓMR			Value remains same	Yes () No ()	
No Bottle OFF ΓMR			Value remains same	Yes () No ()	
NO Cap ON ГMR			Value remains same	Yes() No()	
NO Cap OFF FMR		0000	Value remains same	Yes() No()	
Dossing TMR		-	Value remains same	Yes() No()	
Purzing ON Delay Time	-		Value remains same	Yes() No()	
Purzing OFF Delay Time		Liv	Value remains same	Yes() No()	
Powder Level ON TMR		w w	Value remains same	Yes () No ()	
	Name			S	Sign. & Date
ments/ Remarks				S	Sign. & Date
Function			Department	S	Sign. & Date

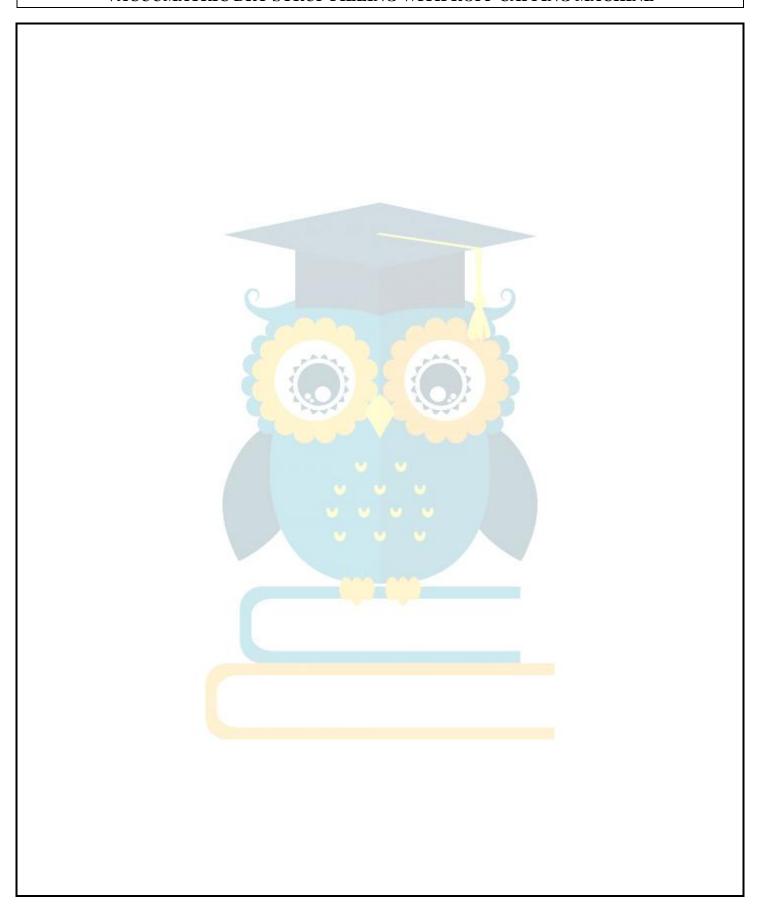


QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	

REVISION No: 00
EFFECTIVE DATE:

PAGE No.: 45 of 63





QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
• • • • • • • • • • • • • • • • • • • •
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 46 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARYS VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.10.0 VERIFICATION OF COMMUNICATION FAILS RECOVERY CONDITION

**Purpose**: Verify and testing of communication fails recovery.

**Scope** : Record the value of process set-parameter after communication fails.

**Procedure** : > Switch "ON" the PLC system.

Enter value in set parameter field in HMI screen and record it.

> Start the machine in auto mode.

➤ While the machine is in running condition, unplug the communication link cable between PLC and HMI.

Take a screen shot or photograph of communication link failure message.

Try to change recipe in HMI screen.

Records the result or error message, if no message appears then write "recipe cannot be changed".

Reconnect the communication link cable after 240 seconds.

Record the values again.

**Discrepancy**: If any Discrepancy is encountered which prevent completion of the report as

originally intended, document the Discrepancy Report.

Acceptance : > In communication link failure condition, message must appear in HMI screen.

When communication link fails the recipe should not be changed or saved.

After communication link reconnect, the set-parameters should not be changed.

Machine works normally after communication failure condition.



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No: 00	

**PAGE No.: 47 of 63** 

**EFFECTIVE DATE:** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARYS VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.10.1 DATA TABLE OF COMMUNICATION FAILURE CONDITION

Procedure	Expected result	Actual Result	Meets acceptance criteria	Sign. & date
Start the system in auto mode and disconnect the PLC – HMI communication cable	"Err" Message should display in HMI screen.		Yes() No()	
Reconnect the PLC – HMI communication cable	Message should remove from HMI screen.		Yes () No ()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

PAGE No.: 48 of 63

Parameter Description	Value Before Communicati on unplug	Value after Communicat ion link reconnect	Expected Result	Meets acceptance criteria	Sign. & date
Run Mode Screen	n				
VIB. Motor			Value remains same	Yes() No()	
Manual Mode Sc	reen				
Main Motor Stop			Value remains same	Yes() No()	
Conveyor 1 Stop	C		Value remains same	Yes() No()	
VIB. Motor Stop		-	Value remains same	Yes() No()	
Conveyor 2 Stop	-		Value remains same	Yes() No()	
Speed Setting Sci	reen				
Main Motor (BPM)			Value remains same	Yes() No()	
Conveyor 1 H.Z			Value remains same	Yes() No()	
Conveyor 2 H.Z		v	Value remains same	Yes () No ()	
Main Motor (BPM)		- Aur	Value remains same	Yes () No ()	
Conveyor 1 H.Z			Value remains same	Yes () No ()	
Conveyor 2 H.Z			Value remains same	Yes () No ()	
Recipe			Value remains same	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
• • • • • • • • • • • • • • • • • • • •
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 49 of 63** 

Parameter Description	Value Before Communicati on unplug	Value after Communicat ion link reconnect	Expected Result	Meets acceptance criteria	Sign. & date
Fimer Setting Sc	ereen				
No Bottle ON ΓMR			Value remains same	Yes ( ) No ( )	
No Bottle OFF FMR			Value remains same	Yes() No()	
NO Cap ON ГMR			Value remains same	Yes() No()	
NO Cap OFF FMR		6000	Value remains same	Yes () No ()	
Dossing TMR	<b>*</b>		Value remains same	Yes() No()	
Purzing ON Delay Time	-		Value remains same	Yes() No()	
Purzing OFF Delay Time		Lur	Value remains same	Yes() No()	
Powder Level ON TMR		6	Value remains same	Yes () No ()	
ments/ Remarks	:			7	
Function	Name	e	Department		Sign. & Date
Function Tested by	Name	e	Department Engineering		Sign. & Date
	Name	e	<del>-</del>		Sign. & Date



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
• • • • • • • • • • • • • • • • • • • •	
REVISION No: 00	

**EFFECTIVE DATE:** 

**PAGE No.: 50 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARYS VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.11.0 VERIFICATION OF ALARMS AND INTERLOCKS

**Purpose**: Verify that all alarms and interlocks of the PLC system and its functions.

**Scope** : Check and record the alarms and interlocks.

**Procedure** : > Start the equipment in normally.

Find cause for particular alarm and record it.

Record the alarm message, which indicate on HMI.

Check and observe the interlock of equipment.

➤ If printing facility available, attached the printout of generated alarms otherwise take photograph of each.

**Discrepancy**: If any Discrepancy is encountered which prevent completion of the report as

originally intended, document the Discrepancy Report.

**Acceptance** : All alarms and interlocks of machine should work properly.

Criteria



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
• • • • • • • • • • • • • • • • • • • •
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 51 of 63** 

Cause	Expected Result	Actual Result	Correction	Meets acceptance criteria	Sign. & date
Emergency			12		J
If emergency push button is pressed	"Emergency"Input (X7)should Active in HMI input Status screen and Auto Cycle Deactivated And The Total System Should Go In Hold Mode.		Release the emergency push button	Yes() No()	
No Bottle Sensor		0000			
If there is no bottle on conveyor or any one bottle is not pass through the bottle sensing sensor.	"No Bottle Sensor" input (X0) should active in HMI input status screen and Auto Cycle Deactivated And The Total System Should Go In Hold Mode.		Check the bottle sensor and maintain the bottle quantity through running filling process.	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 52 of 63** 

Cause	<b>Expected Result</b>	Actual Result	Correction	Meets acceptance criteria	Sign. & date
No Cap Sensor					
If cap level is below than cap sensing sensor Which is placed in cap feeder bowl.	"No Cap Sensor"Input (X2) should Active in HMI input Status screen and Auto Cycle Deactivated And The Total System Should Go In Hold Mode.		Release the emergency push button.	Yes() No()	
Air Low Level					
If air level is less than certain limit	"Air Low Level"input (X21) should active in HMI input status screen and Auto Cycle Deactivated And The Total System Should Go In Hold Mode.		Maintain the air level.	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 53 of 63** 

Cause	Expected Result	Actual Result	Correction	Meets acceptance criteria	Sign. & date
Vacuum Low				1	1
If Vacuum is less than decided level	"Vacuum Low"Input (X22) should Active in HMI input Status screen and Auto Cycle Deactivated And The Total System Should Go In Hold Mode.		Release the emergency push button.	Yes() No()	
Powder Level Low		0 0 0		1	1
If powder level goes below than Powder level checking sensor which placed in powder feeder hooper.	"Powder Level Low"Input (X23) should Active in HMI input Status screen and Auto Cycle Deactivated And The Total System Should Go In Hold Mode.		Maintain the powder quantity in powder feeder hooper. And check the powder level sensor.	Yes() No()	



QUALITY ASSURANCE DEPARTMENT

P	PROTOCOL No.:
• •	• • • • • • • • • • • • • • • • • • • •
R	REVISION No: 00
E	EFFECTIVE DATE:

**PAGE No.: 54 of 63** 

Function	Name	Department	Sign. & Date
Tested by	£	<b>E</b> ngineering	
Verified by	The second	Engineering	
Reviewed by	Au	QA	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00
EFFECTIVE DATE:

**PAGE No.: 55 of 63** 

## OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 3.12.0 VERIFICATION AND RECORD AN INTEGRATED CONTROL LOOP TEST

**Purpose**: Verify the performance of integrated PLC system.

**Scope** : Check and record of an integrated control loop test.

**Procedure** : > Start the equipment in normally.

Login with higher level id and password.

Set require recipe for the test for process start

Start process and observe the set process parameters.

Record the reading of set process parameters until the completion of process.

➤ If printing facility available, attached the printout of whole integrated control loop test.

**Discrepancy**: If any Discrepancy is encountered which prevent completion of the report as

originally intended, document the Discrepancy Report.

Acceptance

Criteria

PLC system should able to control the set process parameter within the

specified limit



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	

**PAGE No.: 56 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

### 3.12.1 DATA TABLE OF CONTROL LOOP TEST

Set Parameters	Set Value
Main Motor Speed (BPM)	
VIB. Motor (RPM)	

Time (min)	Main Motor Speed (BPM)	VIB. Motor (RPM)	Meets acceptance criteria	Sign. & date
		300	Yes () No ()	
	10		Yes()No()	
			Yes () No ()	
		U U U	Yes () No ()	
			Yes () No ()	



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No: 00	

PAGE No.: 57 of 63

**EFFECTIVE DATE:** 

Sr. No	Specified	Actual Observation	Meet Acceptance Criteria
1	Process Should start as per set parameter		Yes () No ()
ents/ Rema	rks:		
Function	Name	<b>Dep</b> artment	Sign. & Date
Tested by	,	Engineering	
	y	Engineering	
Verified b			



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
REVISION No: 00	
<b>EFFECTIVE DATE:</b>	
PAGE No.: 58 of 63	

# OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

Description	of deficiency and its classification*					
Sr.No.	Sr.No. <b>Deficiency</b>					
	ded corrective action, Responsible person					
Sr. No.	Recommended corrective action	Responsibility	Assigned date			
	approval to proceed further (For Category E	) D (; ; ; )				
	neering and date) actions taken (For Category C deficiency)	Quality Assurance (Sign and date)				
Corrective a	and date)		Date			
Corrective a	and date) actions taken (For Category C deficiency)	(Sign and date)	Date			
Corrective a	and date) actions taken (For Category C deficiency) Corrective action taken	(Sign and date) Sign	Date			
Corrective a	and date) actions taken (For Category C deficiency) Corrective action taken  marks: Allowed / Not allowed to proceed fur	(Sign and date) Sign	Date			
Corrective a Sr.  Closure ren Reviewed a	and date) actions taken (For Category C deficiency) Corrective action taken  marks: Allowed / Not allowed to proceed fur and approved by Engineering:	(Sign and date) Sign	Date			
Corrective a Sr.  Closure ren Reviewed a	and date) actions taken (For Category C deficiency) Corrective action taken  marks: Allowed / Not allowed to proceed fur	(Sign and date) Sign	Date			
Closure ren Reviewed a	and date) actions taken (For Category C deficiency) Corrective action taken  marks: Allowed / Not allowed to proceed fur and approved by Engineering: and approved by Quality Assurance:	(Sign and date)  Sign  Sign	Date			
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Closure ren Reviewed a Reviewed a Follow	and date) actions taken (For Category C deficiency) Corrective action taken  marks: Allowed / Not allowed to proceed fur and approved by Engineering: and approved by Quality Assurance:  v-up Compliance (For category C deficiency ded corrective actions taken (Action taken w	(Sign and date)  Sign  Ther  Ther  Ther  Sign  S				

\*Category A: Equipment/instrument/system accepted with deficiency

Reviewed and approved by Engineering:

Category B: Conditional acceptance of equipment, deficiency to be corrected within stipulated period

Category C: Deficiency to be rectified before proceeding further



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:	
•••••	
<b>REVISION No: 00</b>	
<b>EFFECTIVE DATE:</b>	

PAGE No.: 59 of 63

5.0.0	SUMMARY REPO	<u>RT</u>			
			A COOL	2	
		- J.A.			
		S in		3	
	Function	Name	Department		Sign. & Date
	Tested by		Engineering		
	Verified by		Engineering		
	Reviewed by		QA		



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
<b>EFFECTIVE DATE:</b>

**PAGE No.: 60 of 63** 

# OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 6.0.0 TERMINOLOGIES

#### **Access security:**

For protection that ensures system access only to authorized persons on their assigned access level.

#### **Automated system:**

A system that automatically, without human intervention, controls or monitors a specific set of sequential activities; such as a plant process, laboratory function, or data processing operation.

#### **!** Installation Qualification (IQ):

Document evidence that verify the equipment and its sub-system has been installed properly as per the specification.

#### **❖** Operational Qualification (OQ):

Document evidence that the equipment related system or subsystem has been operated properly as per specification.

#### **❖** Validation:

Documented evidence which provides a high degree of assurance that a specific process will consistently produce a product meeting its predetermined specifications and quality attributes.

#### **PLC**:

PLC is an industrial computer control system that continuously monitors the state of input devices and makes decisions based upon a custom program, to control the state of devices connected as outputs.

#### **CPU:**

The **central processing unit** (**CPU**) is the portion of a computer system that carries out the instructions of a computer program, to perform the basic arithmetical, logical, and input/outputoperations of the system.

#### **SOP**: Standard Operating Procedure



QUALITY ASSURANCE DEPARTMENT

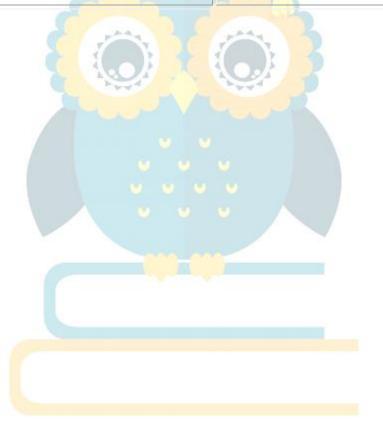
PROTOCOL No.:	
REVISION No: 00	
EFFECTIVE DATE	:

**PAGE No.: 61 of 63** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

### 7.0.0 <u>LIST OF ATTACHMENTS</u>

<u>Sr.</u> <u>No.</u>	Reference	Description Of Attachment	
1	Attachment-1	Master Test Instrument Calibration Certificate	
2	Attachment-2	Field Instrument Calibration Certificate	
3	Attachment-3	HMI Screen	
4	Attachment-4	Communication Fail	





QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
REVISION No: 00

**PAGE No.: 62 of 63** 

**EFFECTIVE DATE:** 

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

### 8.0.0 <u>LIST OF ABBREVIATIONS</u>

<u>Acronym</u>	<b>Description</b>
CPU	→ Central Processing Unit
CGMP	→ Current Good Manufacturing Practices
GAMP	→ Good Automated Manufacturing Practices
GMP	→ Good Manufacturing Practices
ID	→ Identification Number
Ю	→ Input Output
RQ	→ Re-Qualification
PLC	→ Programmable Logic Controller
SOP	→ Standard Operating Procedure
UPS	→ Uninterruptible Power Supply
VAC	→ Volts Alternating Current
VDC	→ Volts Direct Current
VMP	→ Validation Master Plan
HMI	→ Human Machine Interface



QUALITY ASSURANCE DEPARTMENT

PROTOCOL No.:
•••••
REVISION No: 00
EFFECTIVE DATE:

PAGE No.: 63 of 63

OPERATIONAL QUALIFICATION DOCUMENT OF PLC SYSTEM FOR AUTOMATIC ROTARY VACUUMATRIC DRY SYRUP FILLING WITH ROPP CAPPING MACHINE

#### 9.0.0 POST APPROVAL SIGNATURES

The signatures below indicate post approval of this Operational Qualification document and it is executed properly. All variations or discrepancies have been satisfactorily resolved.

Function	Name	Department	Designation	Signature/Date
Executed by	C	Engineering	2	
	1000	h ACY	M	
Reviewed by	7 700	<b>Engineering</b>	1 3	
Reviewed by	100	Production	23	
Reviewed by		Quality Assurance		

Final Approval: Final approval has been given by the following

Function	Name	Designation	Signature/Date
Approved by		Head Quality Assurance	